

# LR Motor Shop Repairs

**EVERY DAY SINCE 1946** 

## **Job Number 101277**

Prepared for Delta Plastics (11016)

8801 Frazier Pike Little Rock AR 72206

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AC Inspection as Found - MOTOR SHOP LR

AC Inspection - Rev. 2: UC 1012/078856801

1.0



FolderID: 101277

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### **AC Inspection as Found**

Delta Plastics (11016)

8801 Frazier Pike Little Rock, AR 72206

AC Inspection - Rev. 2

Location: MOTOR SHOP LR Serial Number: UC 1012/078856801

Description:42.5KW SIEMENS 1800RPM

Hi-Speed Job Number:	101277
Manufacturer:	Siemens
Product Number:	1LG 220-4MA60-Z
Serial Number:	UC 1012/078856801
HP/kW:	42.5 (kW)
RPM:	1770 (RPM)
Frame:	220
Voltage:	460
Current:	66
Phase:	Three
Hz:	60 (Hz)
Enclosure:	TEFC
J-box Included:	Complete
Coupling/Sheave:	Sheave
Bearing RTDs:	No
Stator RTDs:	No
Repair Stage:	Final
Heaters:	No
Winding Type :	Random Wound
Bearing Type:	Rolling Element

Priorities Found: 1 - High

6 - Good

#### **Overall Condition**

- 1. Report Date
- Nameplate Picture



Photos of all six sides of the machine.

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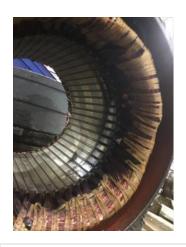












10. Air Gap Variation <10%





4.	Describe the Overall Condition of the Equipment as Received  Filthy	
5.	Distance from the end of the shaft to the Coupling/Sheave	12 inches
Initial	Mechanical/Electrical	
6.	Does Shaft Turn Freely?	
7.	Does Shaft Have Visible Damage?	(No) No
8.	Assembled Shaft Runout	
9.	Assembled Shaft End Play	

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12.	Lead Length	8 Inches
13.	Frame Condition	good
14.	Fan Condition	(P) Pass
15.	Broken or Missing Components	belt sheave broken



Initial Electrical Inspection				
16.	Insulation Resistance/Megger			0 Megohms
17.	Winding Resistance			
	1-2	1-3	2-3	
18.	Perform Surge Test			(F) Fail
19.	Number of Stator Slots			
20.	Stator Condition			bad
21.	Stator Thermistors/Ohms			
22.	Stator Overloads/Ohms			
Mecha	anical Inspection			
23.	Drive End Bearing Brand			
24.	Drive End Bearing Number-			NU213
25.	Drive End Bearing Qty.			1
26.	Drive End Bearing Type		(Roller) R	Roller Bearing
27.	Drive End Lubrication Type		(Grease) Greas	se Lubricated

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28.	3	none	
-	Needs snap ring groove for shaft fit		
29.	Drive End Wavy Washer/Snap-Ring Other Retention Device?		
30.	Drive End Bearing Condition	inner race ejected	
31.	Opposite Drive End Bearing Brand		
32.	Opposite Drive End Bearing Number-	6213	
33.	Opposite Drive End Bearing Qty.	1	
34.	Opposite Drive End Bearing Type	(Ball) Ball Bearing	
35.	Opposite Drive End Lubrication Type	(Grease) Grease Lubricated	
36.	Opposite Drive End Bearing Insulation or Grounding		
37.	7 1 0	· · ·	
38.	Opposite Drive End Bearing Condition	ok	
39.	Drive End Seal	slinger	
40.	11	slinger	
	Inspection		
41.	Rotor Type/Material	(Squirrel Aluminum) Squirrel Cage Aluminum Die Cast	
42.	Growler Test	(Pass) Pass	
43.	Number of Rotor Bars	32	
44.	Rotor Condition	slight iron damage	
	List the Parts needed for the Repair Below		
45.	•		
45. 46.	NU213, 6213 (belt sheave?)	David Maclin	
	NU213, 6213 (belt sheave?)	David Maclin	
46.	NU213, 6213 (belt sheave?)	David Maclin	
46.	NU213, 6213 (belt sheave?)  Signature of Technician that Disassembled Motor	David Maclin	
46.  Mecha 47.	NU213, 6213 (belt sheave?)  Signature of Technician that Disassembled Motor  anical Fits- Rotor	David Maclin	
46.  Mecha 47.	NU213, 6213 (belt sheave?)  Signature of Technician that Disassembled Motor  anical Fits- Rotor  Shaft Runout		
46.  Mecha 47. 48.	Signature of Technician that Disassembled Motor  anical Fits- Rotor Shaft Runout Rotor Runout Drive End Bearing Fit Rotor Body		
46.  Mecha 47.	Signature of Technician that Disassembled Motor  anical Fits- Rotor Shaft Runout Rotor Runout Drive End Bearing Fit Rotor Body  Coupling Fit Closest to Bearing Housing	Opposite Drive End Bearing	
46.  Mecha 47. 48.	Signature of Technician that Disassembled Motor  anical Fits- Rotor Shaft Runout Rotor Runout Drive End Bearing Fit Rotor Body	Opposite Drive End Bearing	
46.  Mecha 47. 48.	Signature of Technician that Disassembled Motor  anical Fits- Rotor Shaft Runout Rotor Runout Drive End Bearing Fit Rotor Body  Coupling Fit Closest to Bearing Housing 0 Degrees 90 Degrees	Opposite Drive End Bearing	
46.  Mecha 47. 48.	Signature of Technician that Disassembled Motor  anical Fits- Rotor Shaft Runout Rotor Runout Drive End Bearing Fit Rotor Body  Coupling Fit Closest to Bearing Housing 0 Degrees  90 Degrees  Coupling Fit Closest to the end of the Shaft	Opposite Drive End Bearing  120 Degrees	
46.  Mecha 47. 48.	Anical Fits- Rotor Shaft Runout Rotor Runout Drive End Bearing Fit  Coupling Fit Closest to Bearing Housing 0 Degrees  90 Degrees	Opposite Drive End Bearing  120 Degrees	
46.  Mecha 47. 48.	Signature of Technician that Disassembled Motor  anical Fits- Rotor Shaft Runout Rotor Runout Drive End Bearing Fit Rotor Body  Coupling Fit Closest to Bearing Housing 0 Degrees  90 Degrees  Coupling Fit Closest to the end of the Shaft	Opposite Drive End Bearing  120 Degrees	
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46.  Mecha 47. 48.	Signature of Technician that Disassembled Motor  anical Fits- Rotor Shaft Runout Rotor Runout Drive End Bearing Fit Rotor Body  Coupling Fit Closest to Bearing Housing 0 Degrees  Coupling Fit Closest to the end of the Shaft 0 Degrees  Drive End Bearing Shaft Fit	Opposite Drive End Bearing  120 Degrees  120 Degrees	
46.  Mecha 47. 48.	Signature of Technician that Disassembled Motor  anical Fits- Rotor Shaft Runout Rotor Runout Drive End Bearing Fit Rotor Body  Coupling Fit Closest to Bearing Housing 0 Degrees 90 Degrees  Coupling Fit Closest to the end of the Shaft 0 Degrees 60 Degrees  Drive End Bearing Shaft Fit 0 Degrees 60 Degrees  2.5595 2.602	Opposite Drive End Bearing  120 Degrees  120 Degrees  120 Degrees	
46.  Mecha 47. 48.  49.  50.	Signature of Technician that Disassembled Motor  anical Fits- Rotor Shaft Runout Rotor Runout Drive End Bearing Fit Coupling Fit Closest to Bearing Housing 0 Degrees  Coupling Fit Closest to the end of the Shaft 0 Degrees  Drive End Bearing Shaft Fit 0 Degrees  2.5595 2.602  Drive End Bearing Shaft Fit Condition	Opposite Drive End Bearing  120 Degrees  120 Degrees  120 Degrees  2.6	
46.  Mecha 47. 48.  49.  50.	Signature of Technician that Disassembled Motor  anical Fits- Rotor Shaft Runout Rotor Runout Drive End Bearing Fit Coupling Fit Closest to Bearing Housing 0 Degrees  Coupling Fit Closest to the end of the Shaft 0 Degrees  Drive End Bearing Shaft Fit 0 Degrees  2.5595  Drive End Bearing Shaft Fit Condition	Opposite Drive End Bearing  120 Degrees  120 Degrees  120 Degrees  (P) Pass	
46.  Mecha 47. 48.  49.  50.	Signature of Technician that Disassembled Motor  anical Fits- Rotor Shaft Runout Rotor Runout Drive End Bearing Fit Rotor Body  Coupling Fit Closest to Bearing Housing 0 Degrees  Coupling Fit Closest to the end of the Shaft 0 Degrees  Drive End Bearing Shaft Fit 0 Degrees  60 Degrees  2.5595 2.602  Drive End Bearing Shaft Fit Condition Opposite Drive End Bearing Shaft Fit	Opposite Drive End Bearing  120 Degrees  120 Degrees  120 Degrees  (P) Pass	

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55	Shaft Air Seal Fits				
00.	Drive End Air Seal	Opposite Drive End Air Seal			
	DIVE ENG All Ocal	Opposite Drive End Air Gear			
Mech	hanical Fits- Bearing Housings				
56.	Drive End - Endbell Bearing Fit				
	0 Degrees	60 Degrees	120 Degrees		
	4.725	4.725	4.725		
57.	Drive End - Endbell Bearing Fit Cond	ition		(P) Pass	
58.	Opposite Drive End - Endbell Bearing	; Fit			
	0 Degrees	60 Degrees	120 Degrees		
	4.7248	4.7249	4.7248		
<b>9</b> 59.	Opposite Drive End - Endbell Bearing	Fit Condition		(P) Pass	
60.	Bearing Cap Condition				
	Drive End Bearing Cap	Opposite Drive End Bearing Cap			
C1	Ok				
61.	End Bell Air Seal Fits	Occasio Di la Fall Air Carl			
	Drive End Air Seal	Opposite Drive End Air Seal			
	Ok				
62.	List Machine Work Needed Below				
_	Machine snap ring grove for DE bearing	g			
62					
65.	Technician			David Maclin	
03.	Technician			David Maclin	
03.	Technician			David Maclin	
63.	Technician			David Maclin	
63.	Technician			David Maclin	
4				David Maclin	
Dynai	mic Balance Report			David Maclin	
Dynai	mic Balance Report Rotor Weight and Balance Grade	Balance Grade		David Maclin	
Dynai	mic Balance Report	Balance Grade		David Maclin	
Dynai	mic Balance Report Rotor Weight and Balance Grade	Balance Grade		David Maclin	
Dynai 64.	mic Balance Report Rotor Weight and Balance Grade Rotor Weight	Balance Grade  Opposite Drive End		David Maclin	
<b>Dynai</b> 64.	mic Balance Report Rotor Weight and Balance Grade Rotor Weight Initial Balance Readings Drive End			David Maclin	
<b>Dynai</b> 64.	mic Balance Report Rotor Weight and Balance Grade Rotor Weight Initial Balance Readings Drive End Final Balance Readings	Opposite Drive End		David Maclin	
<b>Dynai</b> 64.	mic Balance Report Rotor Weight and Balance Grade Rotor Weight Initial Balance Readings Drive End			David Maclin	
64. 65.	mic Balance Report Rotor Weight and Balance Grade Rotor Weight Initial Balance Readings Drive End Final Balance Readings Drive End	Opposite Drive End		David Maclin	
<b>Dynai</b> 64. 65. 66.	mic Balance Report Rotor Weight and Balance Grade Rotor Weight Initial Balance Readings Drive End Final Balance Readings Drive End Technician	Opposite Drive End		David Maclin	
64. 65. 66. <b>67. Rewir</b>	mic Balance Report Rotor Weight and Balance Grade Rotor Weight Initial Balance Readings Drive End Final Balance Readings Drive End Technician	Opposite Drive End Opposite Drive End		David Maclin	
64. 65. 66. <b>67. Rewir</b>	mic Balance Report Rotor Weight and Balance Grade Rotor Weight  Initial Balance Readings Drive End  Final Balance Readings Drive End  Technician  nd  Core Test Results - Watts loss per Po	Opposite Drive End Opposite Drive End		David Maclin	
64. 65. 66. <b>67. Rewir</b>	mic Balance Report Rotor Weight and Balance Grade Rotor Weight Initial Balance Readings Drive End Final Balance Readings Drive End Technician	Opposite Drive End Opposite Drive End		David Maclin	
64. 65. 66. <b>67. Rewir</b>	mic Balance Report Rotor Weight and Balance Grade Rotor Weight Initial Balance Readings Drive End Final Balance Readings Drive End Technician nd Core Test Results - Watts loss per Po	Opposite Drive End Opposite Drive End		David Maclin	
64. 65. 66. <b>Rewir</b> 68.	mic Balance Report Rotor Weight and Balance Grade Rotor Weight Initial Balance Readings Drive End Final Balance Readings Drive End Technician nd Core Test Results - Watts loss per Po	Opposite Drive End Opposite Drive End		David Maclin	
64. 65. 66. <b>Rewir</b> 68.	mic Balance Report Rotor Weight and Balance Grade Rotor Weight Initial Balance Readings Drive End Final Balance Readings Drive End Technician nd Core Test Results - Watts loss per Pore-Burnout Core Hot Spot Test Pre-Burnout	Opposite Drive End Opposite Drive End  ound Post Burnout  Post-Burnout		David Maclin	
64. 65. 66. 67. Rewir 68.	mic Balance Report Rotor Weight and Balance Grade Rotor Weight Initial Balance Readings Drive End Final Balance Readings Drive End Technician nd Core Test Results - Watts loss per Pore-Burnout Core Hot Spot Test Pre-Burnout	Opposite Drive End Opposite Drive End  ound Post Burnout  Post-Burnout		David Maclin	

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72.	Post Rewind Winding Resistance		
	1-2	1-3	2-3
	· <del>-</del>		- 0
73.	Post Rewind Surge Test		
74.	Post Rewind Hi-Pot		
75.	Technician		
Root	Cause of Failure		
76.	Failure locations		
77.	Root cause of failure		
Mecha	anical Fits- Rotor - Post Repair		
78.	Shaft Runout Post Repair		
79.	Rotor Runout Post Repair		
	Drive End Bearing Fit	Rotor Body	Opposite Drive End Bearing
00	Causing Fit Classet to Bearing House	n a Doot Donnin	
80.	Coupling Fit Closest to Bearing Housi	•	420 Dagger
	0 Degrees	90 Degrees	120 Degrees
81.	Coupling Fit Closest to the end of the	Shaft Post Repair	
	0 Degrees	60 Degrees	120 Degrees
82.	Drive End Bearing Shaft Fit Post Rep	air	
	0 Degrees	60 Degrees	120 Degrees
83.	Opposite Drive End Bearing Shaft Fit		100 0
	0 Degrees	60 Degrees	120 Degrees
84.	Shaft Air Seal Fits Post Repair		
	Drive End Air Seal	Opposite Drive End Air Seal	
	21110 2110 7 111 00011		
85.	Shaft Repair Sign-off		
Mecha	anical Fits- Bearing Housings - P	ost Repair	
86.	Drive End - Endbell Bearing Fit Post F	Repair	
	0 Degrees	60 Degrees	120 Degrees
		EVD . D	
87.	11		400 D
	0 Degrees	60 Degrees	120 Degrees
88.	Bearing Cap Condition Post Repair		
50.	Drive End Bearing Cap	Opposite Drive End Bearing Cap	
	Ziiio Ziia Zoaiiiig Gap	opposite zine zine zoemig cap	
89.	End Bell Air Seal Fits Post Repair		
	Drive End Air Seal	Opposite Drive End Air Seal	
	E 10 110		
	End Bell Repair Sign-off		
Asser	·		
	QC Check All Parts for Cleanliness P	•	
92.	Photograph All Major Components pri	or to assembly	
93.			
94.	Assembled Shaft Endplay		

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96. T	Toot Dun Voltogo	. Assembled Shaft Runout			
	Test Run Voltage				
\	Volts	Volts	Volts		
97. T	Test Run Amperage				
P	Amps	Amps	Amps		
00 5	Drive End Vibration Boodings Inches	Dar Sagand			
	Drive End Vibration Readings - Inches				
F	Horizontal	Vertical	Axial		
00 (	Opposite Drive End Vibration Readings	n Inches Der Sesend			
	••				
H	Horizontal	Vertical	Axial		
100. A	Ambient Temperature - Fahrenheit				
101. E	Drive End Bearing Temps - Fahrenheit	t			
5	5 Minutes	10 Minutes	15 Minutes		
102. C	Opposite Drive End Bearing Temps - F	ahrenheit			
5	5 Minutes	10 Minutes	15 Minutes		
103. E	Document Final Condition with Picture	s after paint			
104. F	Final Pics and QC Review				



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- 11. **GOVERNING LAW AND JURISDICTION.** Any controversy arising out of any quotation, the purchase order, the goods sold or delivered, repair or replacement thereof, or any services provided pursuant to any quotation or any purchase order, or these Standard Terms and Conditions shall be governed by the laws of the state of Tennessee without regard to any choice of law provisions and any cause of action related in any manner thereto shall be brought only in the state or federal courts of Shelby County, Tennessee.
- 12. ABANDONED EQUIPMENT. Hi-Speed requires that Buyer promptly pick up or provide shipment instructions for Buyer equipment or other Buyer property in Hi-Speed's possession. If equipment or other Buyer property is left with Hi-Speed and not picked up within six (6) months after Hi-Speed's final action related to the applicable property (e.g. evaluation, teardown, estimate, completion of services), Hi-Speed will consider such property abandoned and may dispose of it in accordance with applicable law. Buyer agrees to hold Hi-Speed harmless for any damage or claim for such abandoned property and acknowledges that Hi-Speed may discard or recycle it at Hi-Speed's sole and absolute discretion. Specifically, Hi-Speed may sell Buyer's abandoned property at a private or public sale and retain the proceeds to offset Hi-Speed's storage, inspection and servicing costs. For the avoidance of doubt, Hi-Speed reserves its statutory and other lawful liens for unpaid charges related to abandoned property.
- 13. FORCE MAJEURE. Neither party shall be responsible for any delay or failure in performance of any party of the quotation, purchase order or these Standard Terms and Conditions to the extent that such delays or failures are caused by fire, flood, earth quake, explosion, war, embargo, government requirement, civil or military authority, acts of God, or any other circumstances beyond its reasonable control and not involving any fault or negligence on the party affected ("Condition"). If any such Condition occurs, the party delayed or unable to perform shall promptly give written notice to the other party and, if such Condition remains at the end of thirty (30) days, the party affected by the other party's delay and inability to perform may elect to (i) terminate such order or part thereof, or (ii) suspend the order for the duration of the Condition, if the Buyer is the suspending party, buy elsewhere comparable material to be sold under the order and apply to any commitment the purchase price of such purchase, and resume performance of the order once the Condition ceases, with an option in the affected party to extend the period of this order up to the length of the time the Condition endures.
- 14. <u>NONWAIVER.</u> No course of dealing or failure of either party to strictly enforce any term, right, or condition of these Standard Terms and Conditions will be construed as a waiver of such term, right or condition. Any waiver by Hi-Speed will only be in writing and will waive no succeeding breach of a term, right or condition.
- 15. <u>ASSIGNMENT.</u> The rights and obligations of the parties shall neither be assigned nor delegated without the prior written consent of the other party. However, any party may assign or delegate its respective rights and obligations, in whole or in part, (i) to any subsidiary, (ii) pursuant to other financing, merger or reorganization or (iii) pursuant to any sale or transfer of substantially all of the assets of the assigning party. These Standard Terms and Conditions shall bind the heirs, successors and assigns of the parties hereto.
- 16. NO INDIVIDUAL LIABILITY. Notwithstanding any other agreement to the contrary, the Buyer agrees that in no event will the Buyer hold and HI-Speed owner, director, officer or employee personally liable for unintentional tortious conduct or conduct that constitutes the breach of any contract between HI-Speed and the Buyer, even if the HI-Speed owner, director, officer or employee is or could be construed to be a party to such contract.